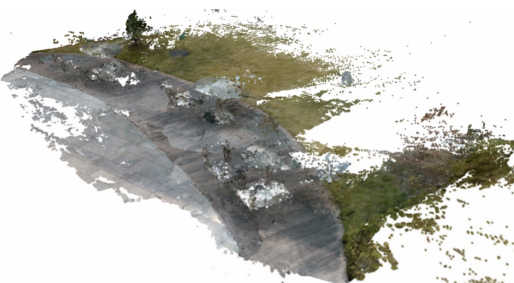


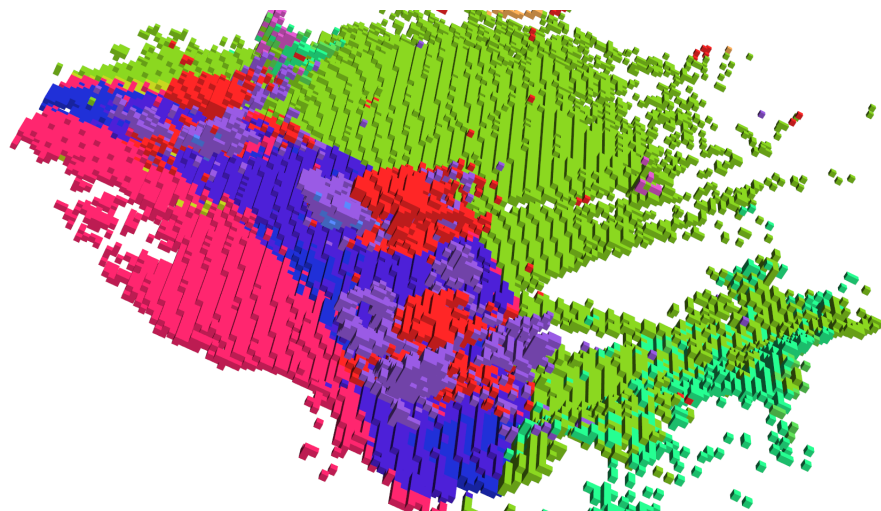
Input RGB-D



3D Gaussian Map



Real-World Open-Vocabulary Occupancy in Outdoor Scene



Input RGB-D



3D Gaussian Map



Real-World Open-Vocabulary Occupancy in Indoor Scene

